

P. Amaral

Department of Mathematics,
University Nova de Lisboa

60th birthday of Immanuel Bomze
Optimization, Game Theory, and Data Analysis

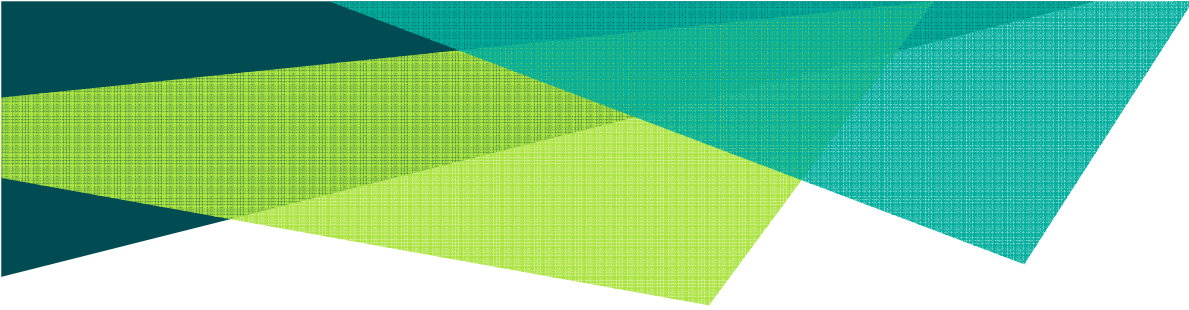
**Copositivity in fractional optimization:
The testimony of a copositive friendship**





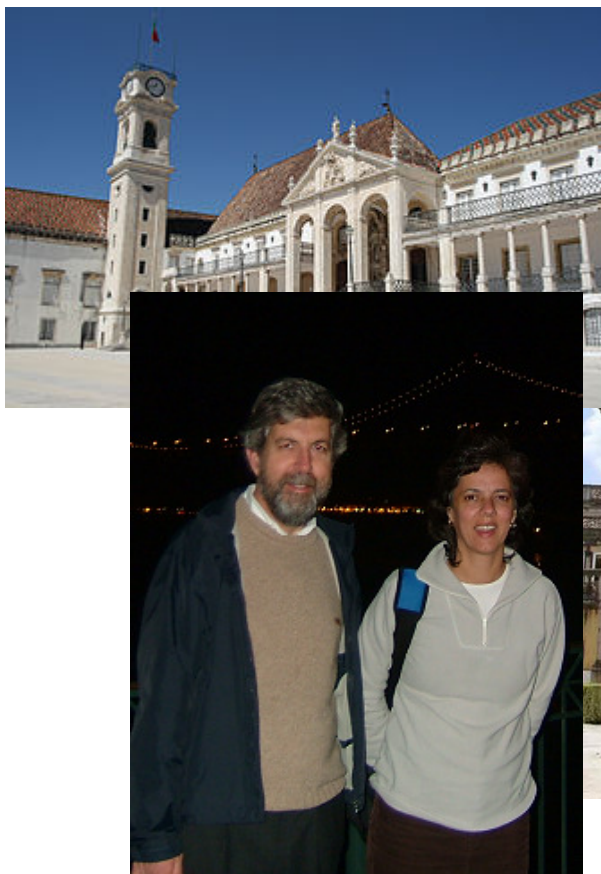
OUTLINE

- TWO EXAMPLES OF DIFFICULT FRACTIONAL PROBLEMS
 - INFEASIBILITY ANALYSIS
 - LINEAR DISCRIMINANT ANALYSIS FOR INTERVAL AND HISTOGRAM DATA
- COMPLETELY POSITIVE FORMULATIONS FOR GENERAL FRACTIONAL PROBLEMS
- LOWER BOUNDS
- MINMAX FRACTIONAL QUADRATIC PROBLEMS
- CONCLUSIONS



First example: Infeasibility in linear systems

2009 - Coimbra





Production planning problem

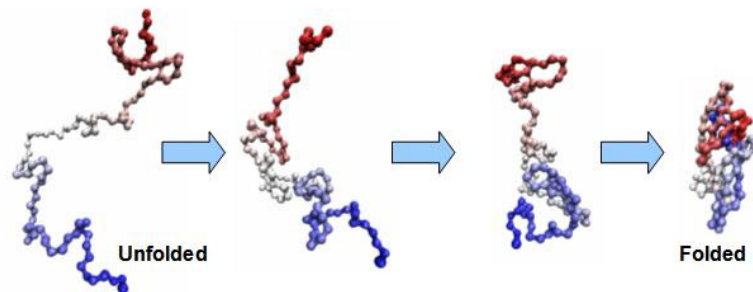
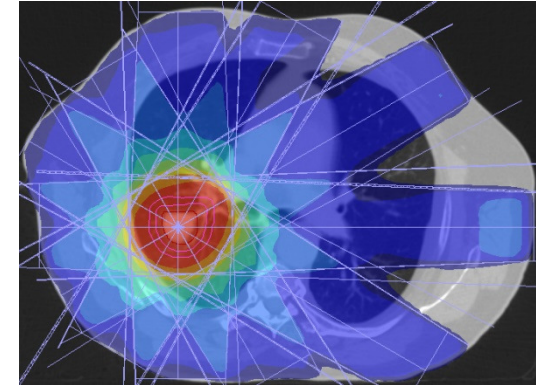
- Amount of products \geq contract
- Consumption \leq raw materials
- Staff \leq availability
- Profit \geq minimum
- Costs \leq limit

Class timetabling problem

- Schedule classes in the week
- Schedule classes in the day
- Rooms available
- Full professor classes timewindow
- No empty hours

Hard and soft constraints

Radiation Treatment Planning



Protein Folding

Digital Video Broadcasting

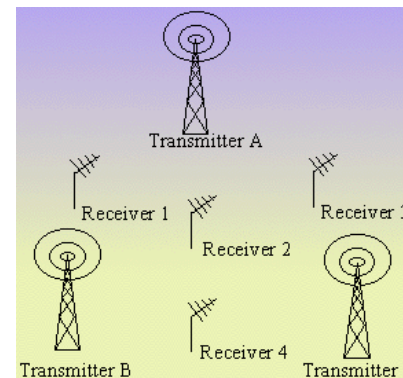
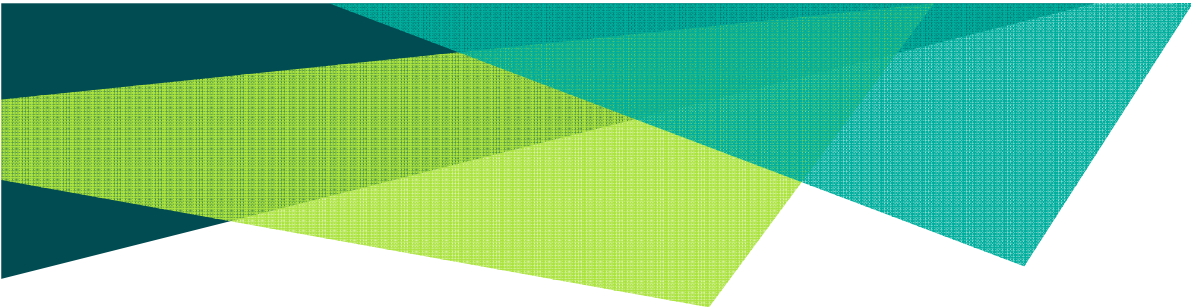
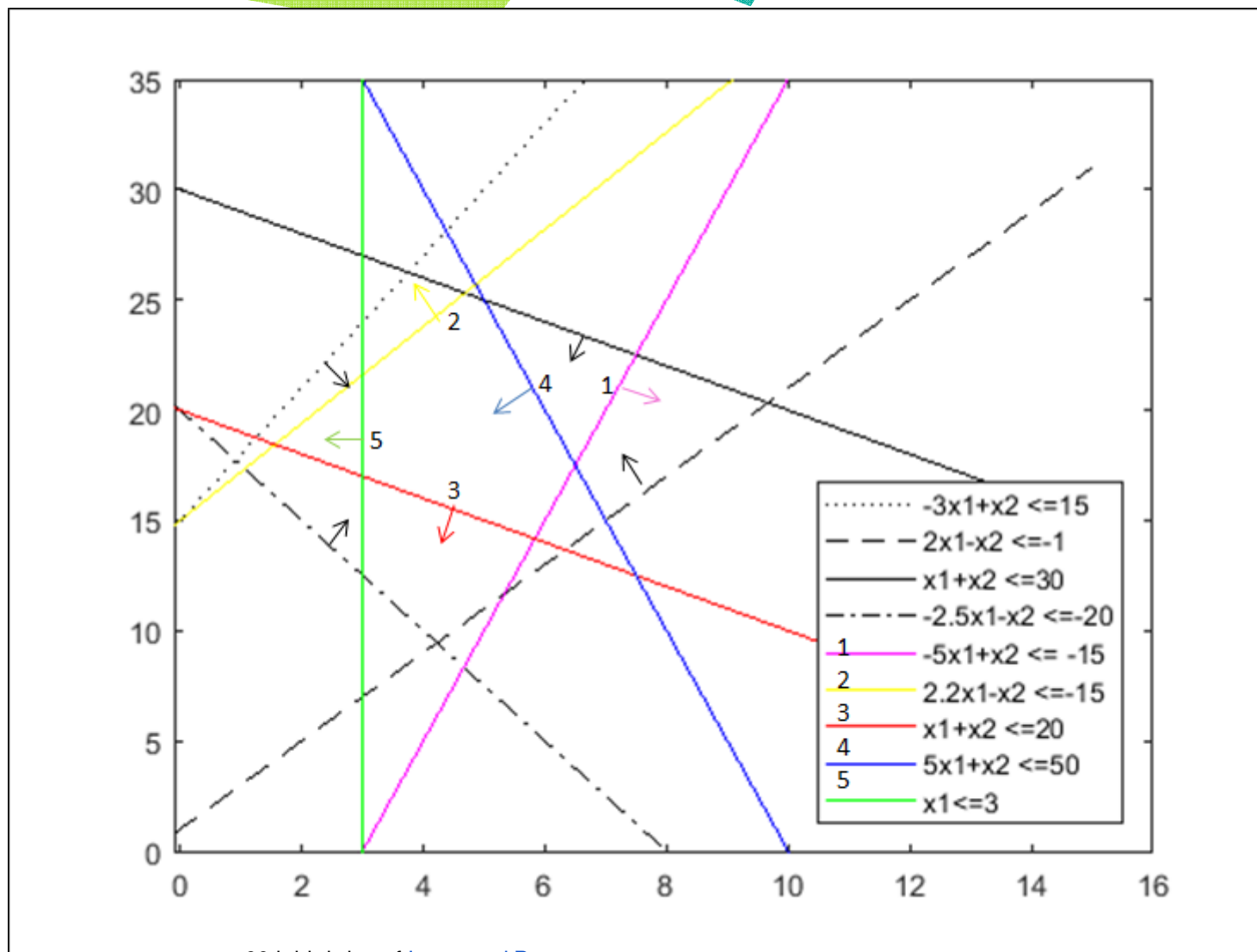
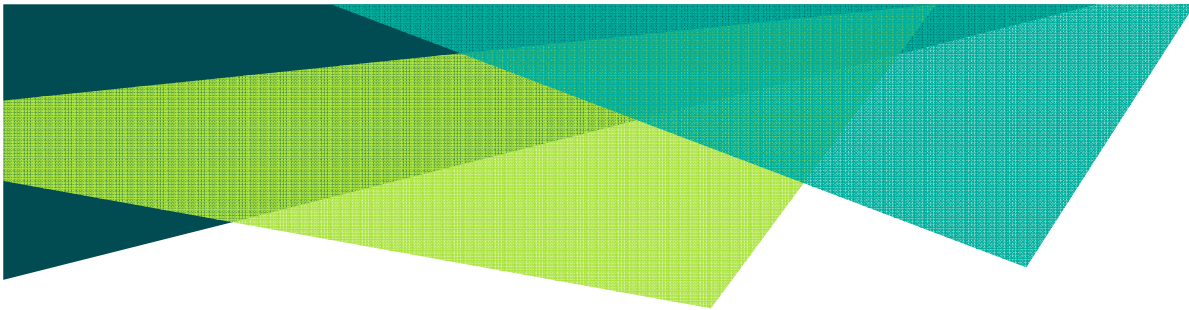


Figure 1: Example of a DVB-T network



$$\begin{array}{l}
 \text{hard constraints} \left\{ \begin{array}{l} -3x_1 + x_2 \leq 15 \\ 2x_1 - x_2 \leq -1 \\ x_1 + x_2 \leq 30 \\ -2.5x_1 - x_2 \leq -20 \end{array} \right. \\
 \text{soft constraints} \left\{ \begin{array}{l} -5x_1 + x_2 \leq -15 \\ 2.2x_1 - x_2 \leq -15 \\ x_1 + x_2 \leq 20 \\ 5x_1 + x_2 \leq 50 \\ x_1 \leq 3 \end{array} \right. \\
 x_1, x_2 \geq 0
 \end{array}$$





$$\min \sum_i \sum_j h_{i,j}^2 + \sum p_i^2$$

$$\begin{aligned} \text{hard constraints} & \begin{cases} -3x_1 + x_2 \leq 15 \\ 2x_1 - x_2 \leq -1 \\ x_1 + x_2 \leq 30 \\ -2.5x_1 - x_2 \leq -20 \end{cases} \\ \text{soft constraints} & \begin{cases} -5x_1 + x_2 \leq -15 \\ 2.2x_1 - x_2 \leq -15 \\ x_1 + x_2 \leq 20 \\ 5x_1 + x_2 \leq 50 \\ x_1 \leq 3 \end{cases} \\ & x_1, x_2 \geq 0 \end{aligned}$$

$$\begin{aligned} \text{hard constraints} & \begin{cases} -3x_1 + x_2 \leq 15 \\ 2x_1 - x_2 \leq -1 \\ x_1 + x_2 \leq 30 \\ -2.5x_1 - x_2 \leq -20 \end{cases} \\ \text{soft constraints} & \begin{cases} (-5 + h_{11})x_1 + (1 + h_{12})x_2 \leq -15 + p_1 \\ (2.2 + h_{21})x_1 + (-1 + h_{22})x_2 \leq -15 + p_2 \\ (1 + h_{31})x_1 + (1 + h_{32})x_2 \leq 20 + p_3 \\ (5 + h_{41})x_1 + (1 + h_{42})x_2 \leq 50 + p_4 \\ (1 + h_{51})x_1 + (0 + h_{52})x_2 \leq 3 + p_5 \end{cases} \\ & x_1, x_2 \geq 0 \end{aligned}$$

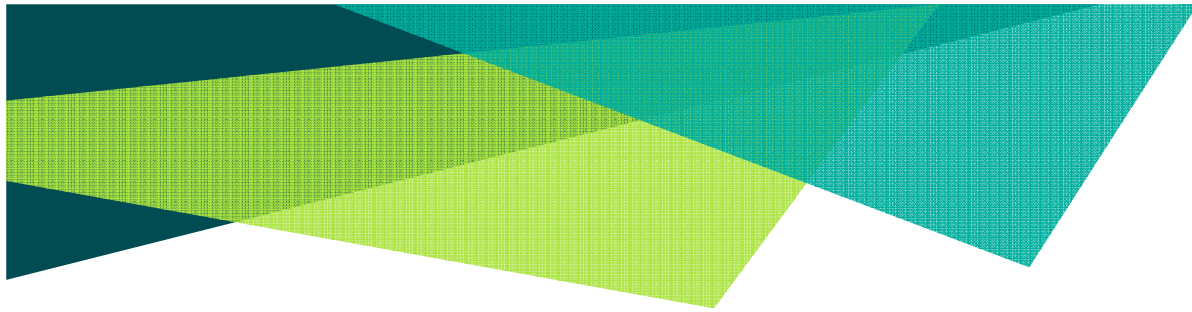


Command Window

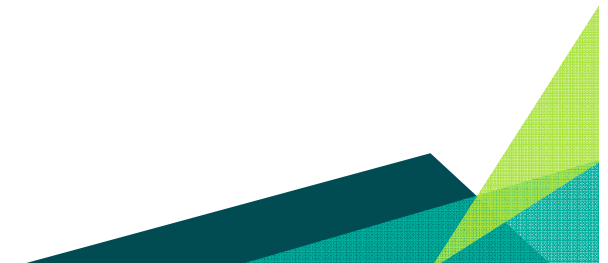
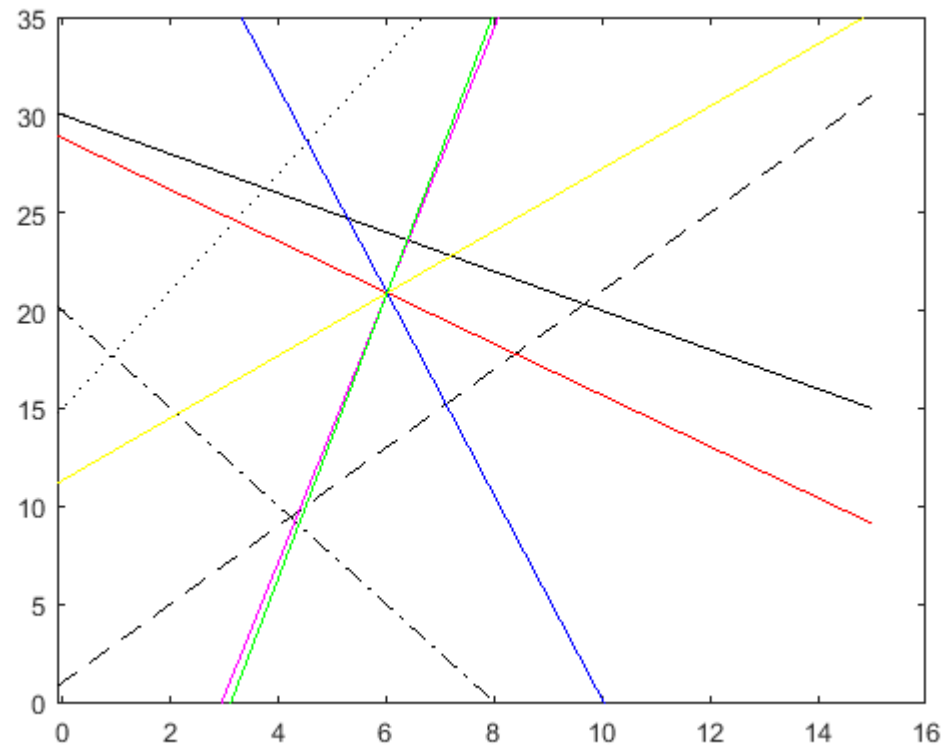
Iteration	Open nodes	Total time	Lower bound	Upper bound
1	1	000:00:02	0.00000	0.307097
1	1	000:00:07	0.259773	0.307097
684	322	000:00:37	0.307074	0.307097
1984	859	000:01:08	0.307085	0.307097
3518	1247	000:01:38	0.307089	0.307097
5174	1482	000:02:08	0.307091	0.307097
6959	1157	000:02:38	0.307093	0.307097
8942	960	000:03:09	0.307094	0.307097
11116	612	000:03:39	0.307095	0.307097
13130	0	000:04:01	0.307096	0.307097

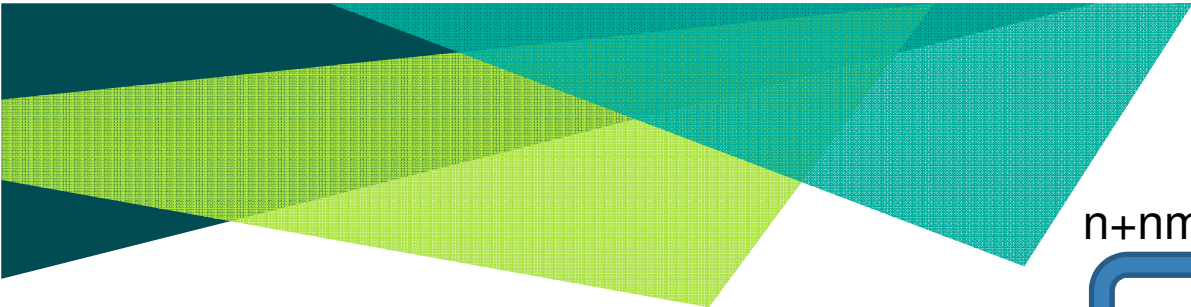
Cleaning up

*** Normal completion ***



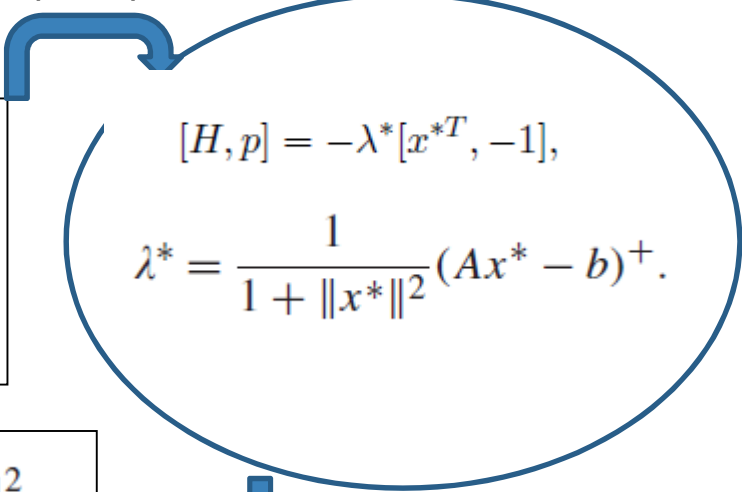
$$\begin{bmatrix} -0.0739 & -0.2569 & 0.0124 \\ -0.0928 & -0.3231 & 0.0153 \\ -0.0879 & -0.3051 & 0.0149 \\ -0.0125 & -0.0434 & 0.0021 \\ -0.0382 & -0.1330 & 0.0063 \end{bmatrix}$$





$$\begin{aligned}
 (P) \text{ Minimize } & \| [H, p] \|_F^2 \\
 \text{subject to } & (A + H)x \leq b + p, \\
 & H \in \mathbb{R}^{m \times n}, \quad p \in \mathbb{R}^m, \quad x \in \mathbf{X}.
 \end{aligned}$$

$n+nm+m$




$$\begin{aligned}
 [H, p] &= -\lambda^* [x^{*T}, -1], \\
 \lambda^* &= \frac{1}{1 + \|x^*\|^2} (Ax^* - b)^+.
 \end{aligned}$$

$$(P) \min_{x \in \mathbf{X}} \frac{\| (Ax - b)^+ \|^2}{1 + \|x\|^2},$$

n

$n+m$



$$\begin{aligned}
 (P_F) : \quad \phi &= \min \frac{\|v\|^2}{1 + \|x\|^2} \\
 \text{subject to } & Ax - v \begin{pmatrix} \leq \\ \leq \end{pmatrix} a \\
 & v_i \geq 0 \text{ for } i = m - r + 1, \dots, m \\
 & x \in \mathbf{X}.
 \end{aligned}$$

Command Window

Done with local search.

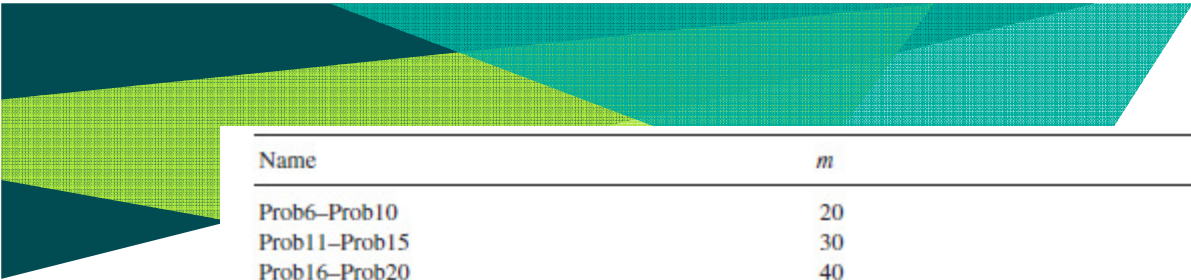
Iteration	Open nodes	Total time	Lower bound	Upper bound
1	1	000:00:00	0.00000	0.307097
1	0	000:00:01	0.307096	0.307097

Cleaning up

*** Normal completion ***

$$x = \begin{bmatrix} 6.0158 \\ 20.9101 \end{bmatrix}$$

$$v = \begin{bmatrix} 5.8310 \\ 7.3247 \\ 6.9259 \\ 0.9892 \\ 3.0158 \end{bmatrix}$$



Name	m	n
Prob6–Prob10	20	10
Prob11–Prob15	30	15
Prob16–Prob20	40	20

Table 3
Computational results

Problems	RLT-BB						
	ND	CPU	ITER	INITUB	VALOPT	NDOPT	NUPDUB
Galenet	1	0	133	3.7313	3.7313	1	0
Itest2	27	0	751	0.4257	0.4257	1	0
Itest6	1	0	37	82 654 535.9118	82 654 535.9118	1	0
Bgprtr	1	0.01	194	1264.5915	1264.5915	1	0
Forest6	1	0.08	471	3458.7896	3458.7896	1	0
Klein1	221	4.62	23 919	34.6664	34.6664	1	0
Woodinfe	1	0	8193	0.0019	0.0019	1	0
Prob4	5	0	217	157.6815	157.6815	1	0
Prob5	4	0	187	262.8295	262.8295	1	0
Prob6	5	0.01	211	315.1673	315.1673	1	0
Prob7	68	0	1196	214.8726	214.8726	1	0
Prob8	1	0	103	2187.0132	2187.0132	1	0
Prob9	20	0.01	522	149.3484	149.3484	1	0
Prob10	29	0	604	250.8560	250.8560	1	0
Prob11	26	0.01	500	396.0405	396.0405	1	0
Prob12	3	0.01	184	1130.5302	1130.5302	1	0
Prob13	12	0.02	489	679.4526	679.4526	1	0
Prob14	6	0.02	382	756.9513	756.9513	1	0
Prob15	476	1.08	23 552	365.3541	364.4484	424	13
Prob16	26	0.12	2052	1121.5359	1121.5359	1	0
Prob17	27	0.13	1980	1092.9802	1092.9802	1	0
Prob18	9	0.04	623	1750.9055	1738.2852	8	4
Prob19	25	0.17	1999	1104.5614	1104.5614	1	0
Prob20	199	1.26	18 410	944.7827	944.7827	1	0

Table 1: Copositive Relaxation versus Gloptipoly 3 and BARON

Instance	Cop R	Time1(s)	Gap	GPM R	Time2(s)	St.	root B.
ABJ5_0				-0.5275	1.045e+00	1	-26.1028
ABJ5_1				-0.5414	1.014e+00	1	-11.8308
ABJ5_2				-0.5089	9.672e-01	1	-11.9631
ABJ5_3				-0.2207	1.310e+00	1	-3.9613
ABJ5_4				-0.9428	9.984e-01	1	-0.8123
ABJ5_5				+0.2225	1.108e+00	1	-2.2940
ABJ5_6				-0.3671	9.828e-01	1	-8.6291
ABJ5_7				-0.0657	8.892e-01	1	-5.1034
ABJ5_8				-0.3708	9.516e-01	1	-0.4031
ABJ5_9				-0.5753	6.708e-01	1	-0.4553
ABJ10_0				-0.1962	7.010e+02	1	-23.9325
ABJ10_1				-0.4882	5.737e+02	1	-0.4587
ABJ10_2				+0.4288	6.395e+02	1	-3.4076
ABJ10_3				-0.1840	6.298e+02	1	-12.3357
ABJ10_4				-0.2689	5.122e+02	1	-0.2635
ABJ10_5				-0.6198	6.619e+02	1	-55.5414
ABJ10_6				-0.8749	7.123e+02	1	-0.8265
ABJ10_7				-0.0760	6.219e+02	1	-25.4559
ABJ10_8				-0.4558	6.239e+02	1	-0.5056
ABJ10_9				-0.1794	6.183e+02	1	-0.1919
ABJ50_0				O of M	-		-502.4740
ABJ50_1				O of M	-		-0.7856
ABJ50_2				O of M	-		-0.6135
ABJ50_3				O of M	-		-1463.1800
ABJ50_4				O of M	-		-451.7790
ABJ50_5				O of M	-		-0.3962
ABJ50_6				O of M	-		-989.5200
ABJ50_7				O of M	-		-0.4914
ABJ50_8				O of M	-		-490.0360
ABJ50_9				O of M	-		-626.8870
ABJ80_0				O of M	-		-1394.8500
ABJ80_1				O of M	-		-0.4472
ABJ80_2				O of M	-		-0.6681
ABJ80_3				O of M	-		-1849.5000
ABJ80_4				O of M	-		-0.6528
ABJ80_5				O of M	-		-0.3511
ABJ80_6				O of M	-		-2488.4700
ABJ80_7				O of M	-		-1487.1000
ABJ80_8				O of M	-		-736.0130
ABJ80_9				O of M	-		-0.5177

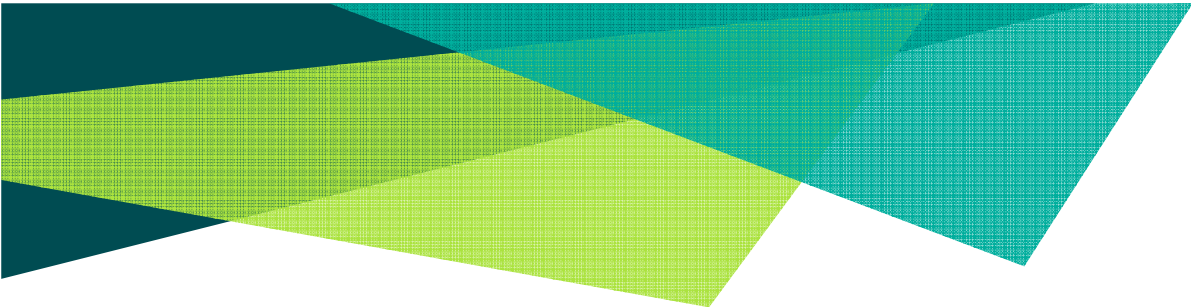


Second example: Linear Discriminant Analysis for Interval and Histogram Data

Paula Brito , Sónia Dias

NEWFRIENDS=FRIENDS(Immanuel)





$$\max_{x \in \mathbb{R}^{n+}} \frac{x^T B x}{x^T W x}$$

Command Window

B =

0.0035	-0.0032	0.0012	-0.0004	-0.0017	0.0026	-0.0013	0.0018
-0.0032	0.0035	-0.0004	0.0012	0.0026	-0.0017	0.0018	-0.0013
0.0012	-0.0004	0.0012	0.0007	0.0005	0.0017	0.0001	0.0011
-0.0004	0.0012	0.0007	0.0012	0.0017	0.0005	0.0011	0.0001
-0.0017	0.0026	0.0005	0.0017	0.0027	-0.0002	0.0018	-0.0004
0.0026	-0.0017	0.0017	0.0005	-0.0002	0.0027	-0.0004	0.0018
-0.0013	0.0018	0.0001	0.0011	0.0018	-0.0004	0.0013	-0.0005
0.0018	-0.0013	0.0011	0.0001	-0.0004	0.0018	-0.0005	0.0013

>> W

W =

0.0553	-0.0527	0.0563	-0.0541	-0.0511	0.0527	-0.0565	0.0580
-0.0527	0.0553	-0.0541	0.0563	0.0527	-0.0511	0.0580	-0.0565
0.0563	-0.0541	0.0662	-0.0590	-0.0544	0.0559	-0.0594	0.0623
-0.0541	0.0563	-0.0590	0.0662	0.0559	-0.0544	0.0623	-0.0594
-0.0511	0.0527	-0.0544	0.0559	0.0557	-0.0507	0.0565	-0.0517
0.0527	-0.0511	0.0559	-0.0544	-0.0507	0.0557	-0.0517	0.0565
-0.0565	0.0580	-0.0594	0.0623	0.0565	-0.0517	0.0671	-0.0604
0.0580	-0.0565	0.0623	-0.0594	-0.0517	0.0565	-0.0604	0.0671

```

Command Window
This BARON run may utilize the following subsolver(s)
For LP: COIN LP
For NLP: COIN IPOPT with MUMPS and METIS

=====
Preprocessing found feasible solution with value -.388222693216
Doing local search
Preprocessing found feasible solution with value -.611023475810
Solving bounding LP
Starting multi-start local search
Done with local search

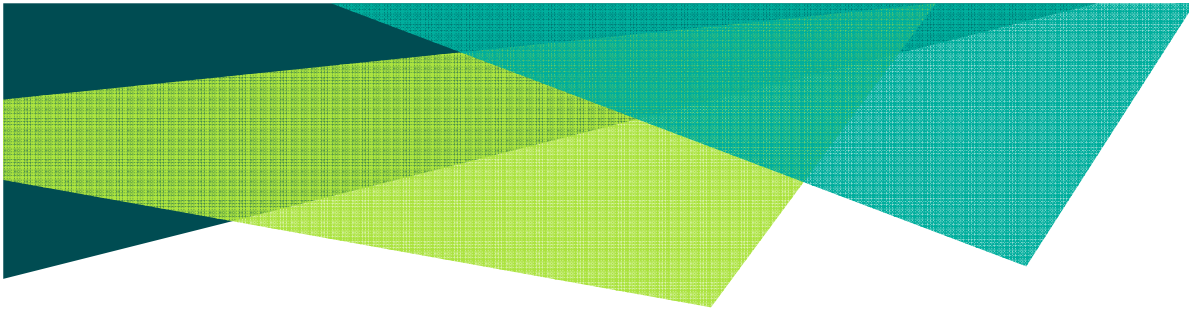
=====
Iteration      Open nodes      Total time      Lower bound      Upper bound
          1              1          000:00:01    -0.100000E+52    -0.611023
=====

User did not provide appropriate variable bounds.
Some model expressions are unbounded.
We may not be able to guarantee globality.
Number of missing variable or expression bounds =      1
Number of variable or expression bounds autoset =      1
=====
          1              1          000:00:02    -0.100000E+09    -0.611023
        1000             514          000:00:30    -0.100000E+09    -0.611023

Cleaning up

fx *** Max. allowable BaR iterations reached ***

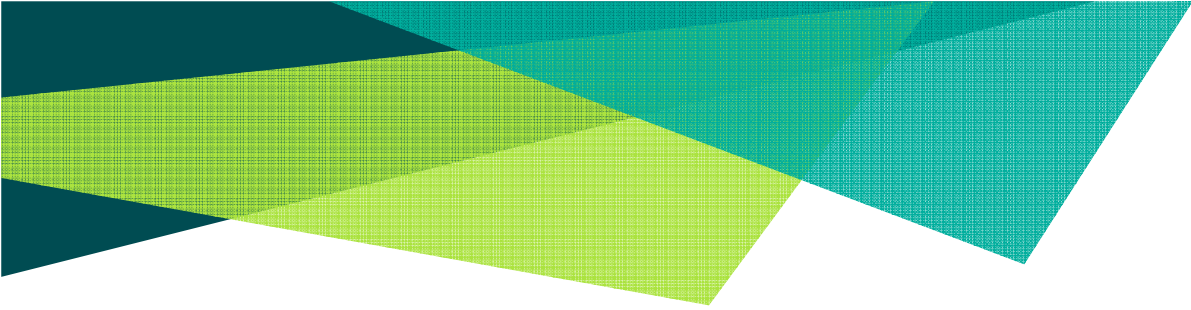
```



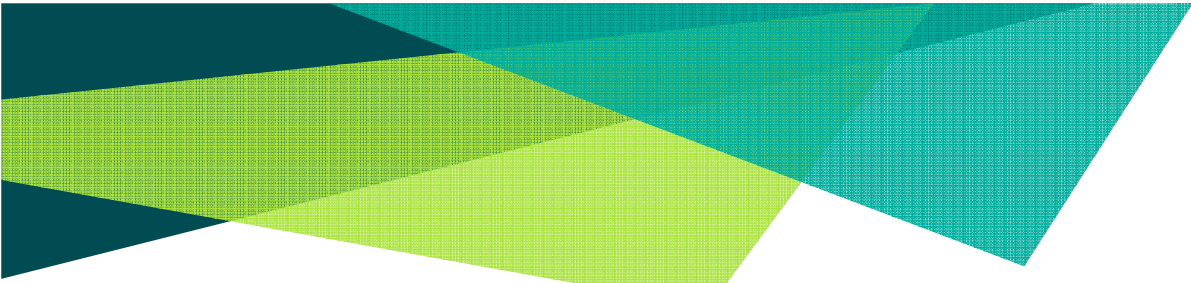
Size 8x8

UB	Sol	
1,00E+09	6,17E-02	
1,00E+09	1,47E-01	
1,00E+09	2,56E-01	
1,00E+09	1,53E-01	
1,00E+09	1,19E-01	
1,00E+09	1,91E-01	
1,00E+09	2,24E-01	
1,00E+09	2,42E-01	
1,00E+09	1,32E-01	
1,00E+09	3,46E-01	





Fractional Quadratic Problems



$$\psi = \min \left\{ f(\mathbf{x}) = \frac{\mathbf{x}^\top C \mathbf{x} + 2\mathbf{c}^\top \mathbf{x} + \gamma}{\underbrace{\mathbf{x}^\top B \mathbf{x} + 2\mathbf{b}^\top \mathbf{x} + \beta}_{p(\mathbf{x})}} : \underbrace{\mathbf{x} \in \mathbb{R}_+^n : A\mathbf{x} = \mathbf{a}}_{\mathcal{T}} \right\}$$

Compactness of \mathcal{T} and strict positivity of p over this set implies that

$$\psi = \min \left\{ f(\mathbf{x}) = \frac{\mathbf{x}^\top C \mathbf{x} + 2\mathbf{c}^\top \mathbf{x} + \gamma}{p(\mathbf{x})} : \mathbf{x} \in \mathcal{T} \right\}$$

always has an optimal solution (primal attainability).

Conic Optimization

Reformulated as a conic optimization problem

$$\begin{array}{ll}\min & \langle C, X \rangle \\ \text{s.t.} & \langle A^i, X \rangle = b_i \quad i \in \{1, \dots, m\} \\ & X \in \mathcal{K}\end{array}$$

$$\begin{array}{ll}x \in \mathcal{K} = R_n^+ & \text{if } x \geq 0 \\ X \in \mathcal{K} \text{ (Positive Semidefinite)} & \text{if } y^T X y \geq 0 \\ X \in \mathcal{K} \text{ (Copositive)} & \text{if } y^T X y \geq 0 \quad \forall y \geq 0 \\ X \in \mathcal{K} \text{ (D-Copositive)} & \text{if } y^T X y \geq 0 \quad \forall y \in D \\ X \in \mathcal{K} \text{ (Completely Positive)} & \text{if } X = Y^T Y, Y \geq 0\end{array}$$

Conic Optimization

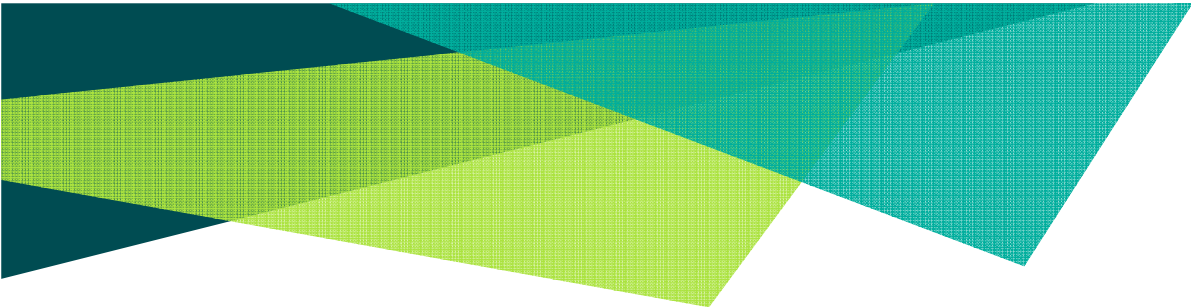
Reformulated as a conic optimization problem

$$\begin{array}{ll}\min & \langle C, X \rangle \\ \text{s.t.} & \langle A^i, X \rangle = b_i \quad i \in \{1, \dots, m\} \\ & X \in \mathcal{K}\end{array}$$

$$x^T A x \longrightarrow \langle A, x x^T \rangle \longrightarrow \langle A, X \rangle \quad X \in \mathcal{C}_n^* \wedge X \text{ is of rank one} = \mathcal{C}_n^{*rk1}$$

$$\mathcal{C}_n^* = \{D \in \mathcal{M}_n : D = Y Y^T, Y \text{ an } n \times k \text{ matrix with } Y \geq O\}$$

Relaxation to a more manageable cone – LOWER BOUND

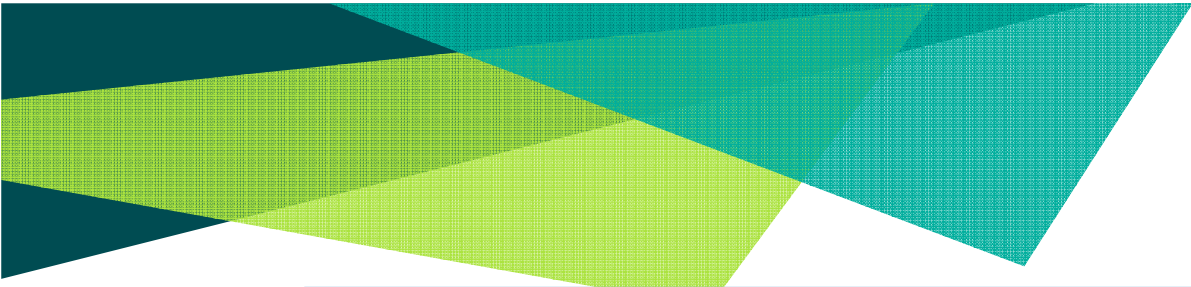


$$\begin{aligned}\psi &= \min \left\{ f(\mathbf{x}) = \frac{\mathbf{x}^\top C \mathbf{x} + 2\mathbf{c}^\top \mathbf{x} + \gamma}{\mathbf{x}^\top B \mathbf{x} + 2\mathbf{b}^\top \mathbf{x} + \beta} : A\mathbf{x} = \mathbf{a}, \mathbf{x} \in \mathbb{R}_+^n \right\} \\ &= \min \{ \overline{C} \cdot X : \overline{B} \cdot X = 1, \overline{A} \cdot X = 0, X \in \mathcal{C}_{n+1}^* \}.\end{aligned}$$

cone of completely positive matrices

$$\mathcal{C}_n^* = \{ D \in \mathcal{M}_n : D = YY^\top, Y \text{ an } n \times k \text{ matrix with } Y \geq O \}$$

$$\overline{A} = \begin{bmatrix} \mathbf{a}^\top \mathbf{a} & -\mathbf{a}^\top A \\ -A^\top \mathbf{a} & A^\top A \end{bmatrix}, \quad \overline{B} = \begin{bmatrix} \beta & \mathbf{b}^\top \\ \mathbf{b} & B \end{bmatrix}, \quad \overline{C} = \begin{bmatrix} \gamma & \mathbf{c}^\top \\ \mathbf{c} & C \end{bmatrix}$$

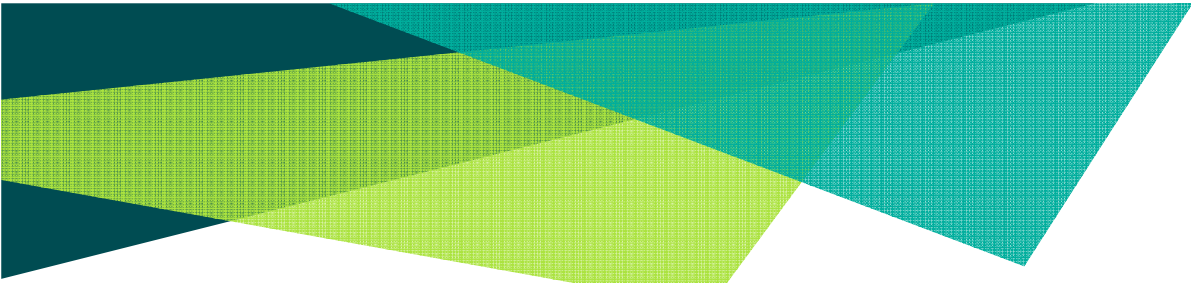


$$\psi = \min \left\{ f(\mathbf{x}) = \frac{\mathbf{x}^\top C \mathbf{x} + 2\mathbf{c}^\top \mathbf{x} + \gamma}{\underbrace{\mathbf{x}^\top B \mathbf{x} + 2\mathbf{b}^\top \mathbf{x} + \beta}_{p(\mathbf{x})}} : \underbrace{\mathbf{x} \in \mathbb{R}_+^n : A\mathbf{x} = \mathbf{a}}_{\mathcal{T}} \right\}$$

Compactness of \mathcal{T} and strict positivity of p over this set implies that

$$\psi = \min \left\{ f(\mathbf{x}) = \frac{\mathbf{x}^\top C \mathbf{x} + 2\mathbf{c}^\top \mathbf{x} + \gamma}{p(\mathbf{x})} : \mathbf{x} \in \mathcal{T} \right\}$$

always has an optimal solution (primal attainability).

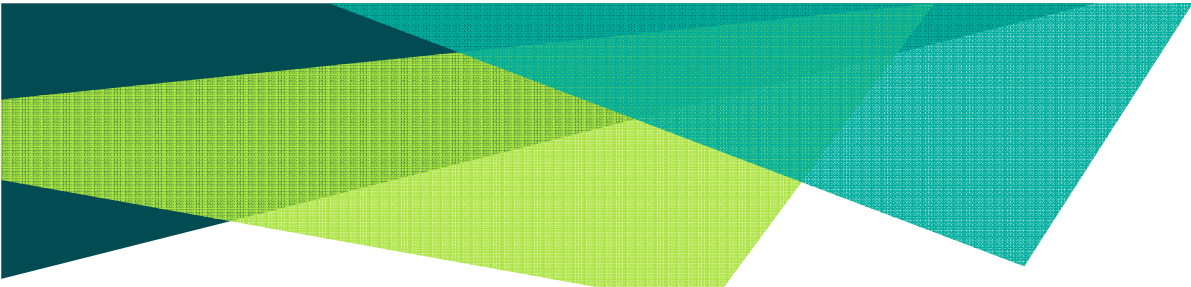


$$\psi = \min \left\{ f(\mathbf{x}) = \frac{\mathbf{x}^\top C \mathbf{x} + 2\mathbf{c}^\top \mathbf{x} + \gamma \mathbf{1}}{\mathbf{x}^\top B \mathbf{x} + 2\mathbf{b}^\top \mathbf{x} + \beta \mathbf{1}} : \mathbf{x} \in \mathbb{R}_+^n : A\mathbf{x} = \mathbf{a} \mathbf{1} \right\}$$

$$\mathbf{z} = \begin{bmatrix} \mathbf{1} \\ \mathbf{x} \end{bmatrix}$$

$$\overline{A} = \begin{bmatrix} \mathbf{a}^\top \mathbf{a} & -\mathbf{a}^\top A \\ -A^\top \mathbf{a} & A^\top A \end{bmatrix}, \quad \overline{B} = \begin{bmatrix} \beta & \mathbf{b}^\top \\ \mathbf{b} & B \end{bmatrix}, \quad \overline{C} = \begin{bmatrix} \gamma & \mathbf{c}^\top \\ \mathbf{c} & C \end{bmatrix}$$

$$A\mathbf{x} = \mathbf{a} \Leftrightarrow [-\mathbf{a}, A]\mathbf{z} = \mathbf{0} \Leftrightarrow \mathbf{z}^\top \overline{A} \mathbf{z} = 0$$



$$\psi = \min \left\{ f(\mathbf{x}) = \frac{\mathbf{x}^\top C \mathbf{x} + 2\mathbf{c}^\top \mathbf{x} + \gamma}{\mathbf{x}^\top B \mathbf{x} + 2\mathbf{b}^\top \mathbf{x} + \beta} : \mathbf{x} \in \mathbb{R}_+^n : A\mathbf{x} = \mathbf{a} \right\}$$

$$\overline{A} = \begin{bmatrix} \mathbf{a}^\top \mathbf{a} & -\mathbf{a}^\top A \\ -A^\top \mathbf{a} & A^\top A \end{bmatrix}, \quad \overline{B} = \begin{bmatrix} \beta & \mathbf{b}^\top \\ \mathbf{b} & B \end{bmatrix}, \quad \overline{C} = \begin{bmatrix} \gamma & \mathbf{c}^\top \\ \mathbf{c} & C \end{bmatrix}.$$

$$\psi = \min \left\{ \frac{\mathbf{z}^\top \overline{C} \mathbf{z}}{\mathbf{z}^\top \overline{B} \mathbf{z}} : \mathbf{z} \in \mathbb{R}_+^{n+1}, z_1 = 1, \mathbf{z}^\top \overline{A} \mathbf{z} = 0 \right\}.$$

$$\psi = \min \left\{ f(\mathbf{x}) = \frac{\mathbf{x}^\top C \mathbf{x} + 2\mathbf{c}^\top \mathbf{x} + \gamma}{\underbrace{\mathbf{x}^\top B \mathbf{x} + 2\mathbf{b}^\top \mathbf{x} + \beta}_{p(x)}} : \underbrace{\mathbf{x} \in \mathbb{R}_+^n : A\mathbf{x} = \mathbf{a}}_{\mathcal{T}} \right\}$$

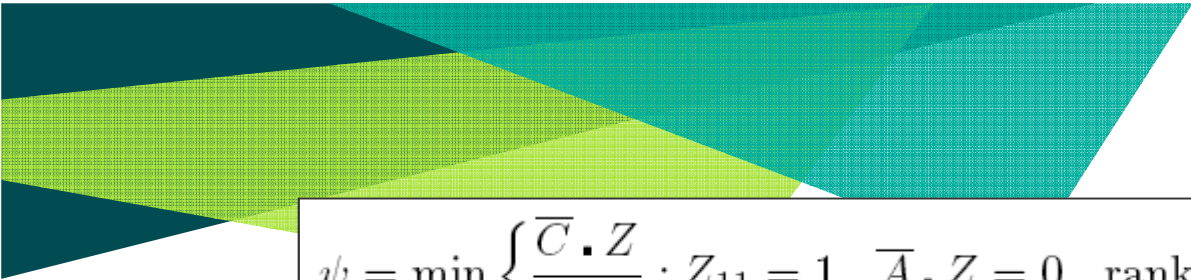
$$\psi = \min \left\{ \frac{\mathbf{z}^\top \overline{C} \mathbf{z}}{\mathbf{z}^\top \overline{B} \mathbf{z}} : \mathbf{z} \in \mathbb{R}_+^{n+1}, z_1 = 1, \mathbf{z}^\top \overline{A} \mathbf{z} = 0 \right\}.$$

$$Z = \mathbf{z} \mathbf{z}^\top$$

$$\mathbf{z}^\top \overline{A} \mathbf{z} = \overline{A} \cdot Z$$

$$\overline{A}, \text{ psd } Z_{11} = z_1^2 \text{ and } \mathbf{z} \in \mathbb{R}_+^{n+1}$$

$$\psi = \min \left\{ \frac{\overline{C} \cdot Z}{\overline{B} \cdot Z} : Z_{11} = 1, \overline{A} \cdot Z = 0, \text{rank}(Z) = 1, Z \in \mathcal{C}_{n+1}^* \right\}$$



$$\psi = \min \left\{ \frac{\overline{C} \cdot Z}{\overline{B} \cdot Z} : Z_{11} = 1, \overline{A} \cdot Z = 0, \text{rank}(Z) = 1, Z \in \mathcal{C}_{n+1}^* \right\}$$

$$Z_{11} = 1 \leftarrow Z_{11} > 0$$

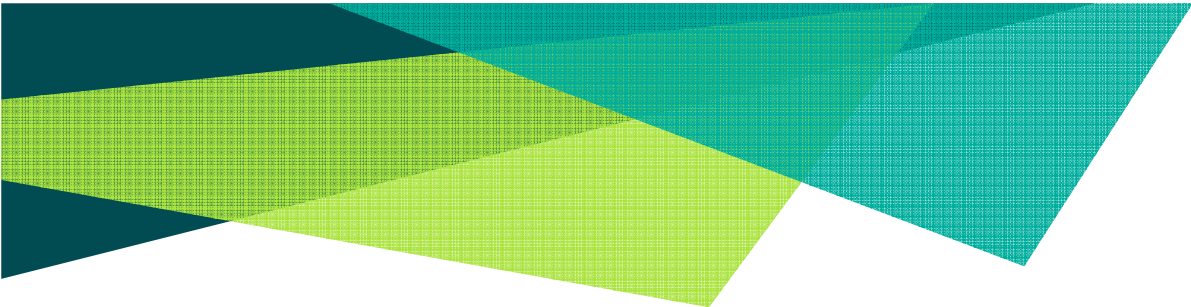
.

$$X = \frac{1}{\overline{B} \cdot Z} Z \in \mathcal{C}_{n+1}^*$$

which also has rank one with $X_{11} > 0$ and satisfies

$$\overline{B} \cdot X = 1$$

$$\psi = \min \{ \overline{C} \cdot X : \overline{B} \cdot X = 1, \overline{A} \cdot X = 0, \text{rank}(X) = 1, X_{11} > 0, X \in \mathcal{C}_{n+1}^* \}$$



$$\min \left\{ \overline{C} \bullet X : \overline{B} \bullet X = 1, \overline{A} \bullet X = 0, \text{rank}(X) = 1, \right. \\ \left. X_{11} > 0, X \in \mathcal{C}_{n+1}^* \right\}.$$

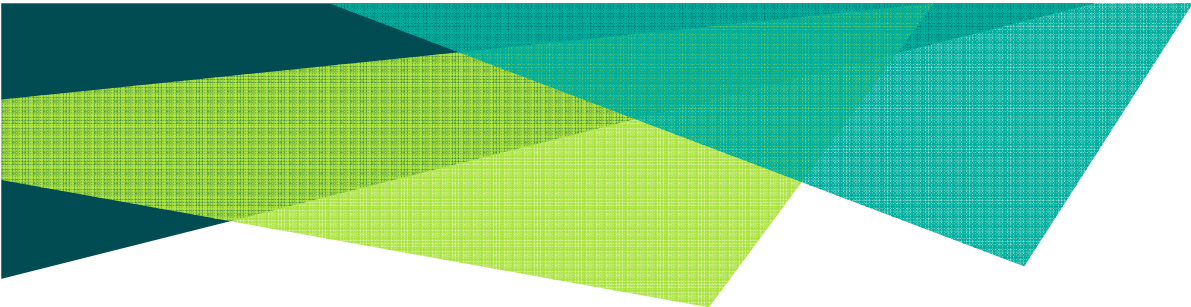
$$\min \left\{ \overline{C} \bullet X : \overline{B} \bullet X = 1, \overline{A} \bullet X = 0, X \in \mathcal{C}_{n+1}^* \right\}.$$

Lemma 2 *Under the model assumptions (10),*

$$\begin{aligned} & \{X \in \mathcal{C}_{n+1}^* : \overline{B} \bullet X = 1, \overline{A} \bullet X = 0\} \\ &= \text{conv} \left\{ \mathbf{z}\mathbf{z}^\top : \mathbf{z} \in \mathbb{R}_+^{n+1} : z_1 > 0, \mathbf{z}^\top \overline{B}\mathbf{z} = 1, \overline{A}\mathbf{z} = \mathbf{o} \right\}. \end{aligned}$$

$$\left. \begin{aligned} & \mathcal{T} = \{\mathbf{x} \in \mathbb{R}_+^n : A\mathbf{x} = \mathbf{a}\} \neq \emptyset; \\ & \ker A \cap \mathbb{R}_+^n = \{\mathbf{o}\} \iff A\mathbf{y} \neq \mathbf{o} \text{ if } \mathbf{y} \in \mathbb{R}_+^n \setminus \{\mathbf{o}\}; \\ & \overline{B} \text{ is strictly } \Gamma_{\overline{A}}\text{-copositive: } \mathbf{z}^\top \overline{B}\mathbf{z} > 0 \text{ if } \overline{A}\mathbf{z} = \mathbf{o}, \mathbf{z} \in \mathbb{R}_+^n \setminus \{\mathbf{o}\}. \end{aligned} \right\} \quad (10)$$

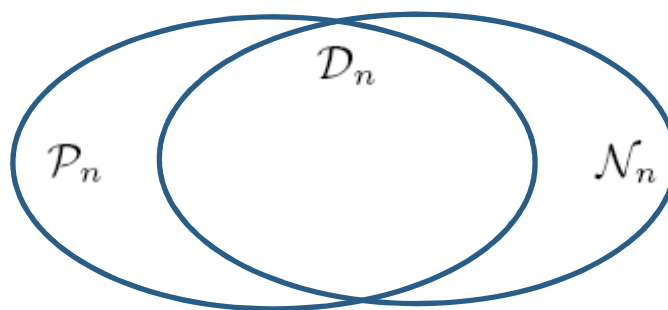
$$\Gamma_{\overline{A}} = \{\mathbf{z} \in \mathbb{R}_+^{n+1} : \overline{A}\mathbf{z} = \mathbf{o}\}.$$



$$\psi = \min \left\{ \overline{C} \bullet X : \overline{B} \bullet X = 1, \overline{A} \bullet X = 0, \text{rank}(X) = 1, \right. \\ \left. X_{11} > 0, X \in \mathcal{C}_{n+1}^* \right\}. \quad (13)$$

$$\min \left\{ \overline{C} \bullet X : \overline{B} \bullet X = 1, \overline{A} \bullet X = 0, X \in \mathcal{C}_{n+1}^* \right\}. \quad (14)$$

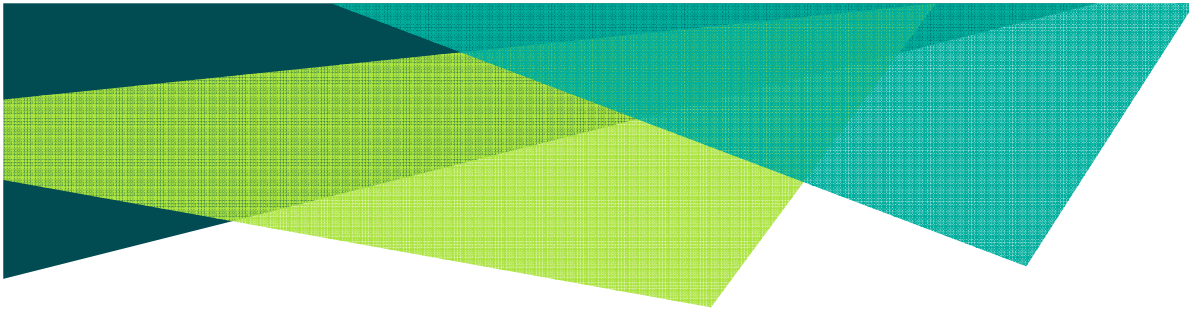
Theorem 1 *Under the model assumptions (10), problems (13) and (14) are equivalent. Moreover, there is always an optimal solution of the form $Z^* = Z_{11}^* \mathbf{z} \mathbf{z}^\top$ to (14) with $\mathbf{z}^\top = [1, (\mathbf{x}^*)^\top]$ which encodes in $\mathbf{x}^* \in \mathcal{T}$ an optimal solution to (4).*



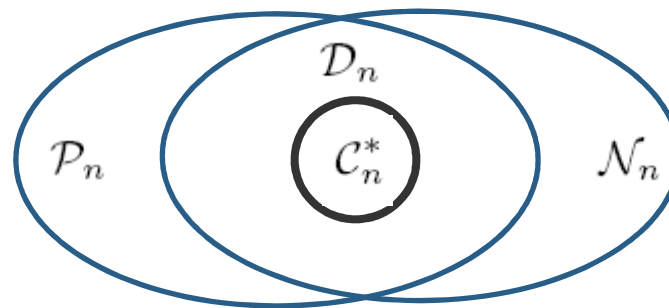
cone of symmetric psd $n \times n$ matrices cone of nonnegative symmetric matrices

$$\mathcal{P}_n \cap \mathcal{N}_n = \mathcal{D}_n$$

cone of doubly nonnegative matrices



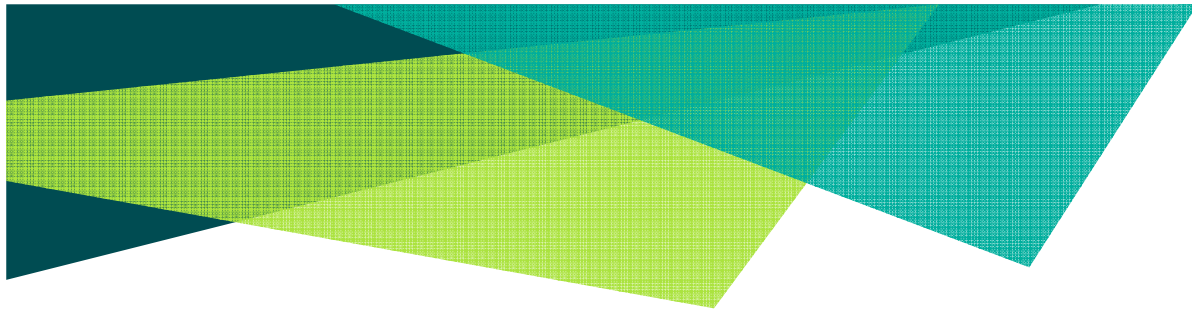
\mathcal{C}_n^* cone of completely positive matrices



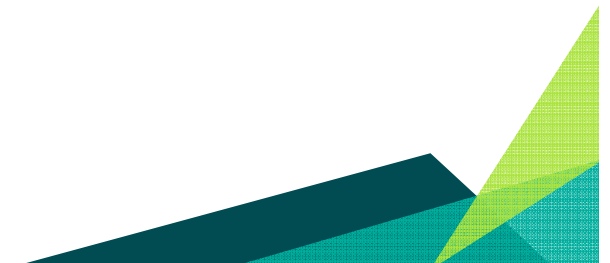
$$\mathcal{P}_n \cap \mathcal{N}_n = \mathcal{D}_n$$

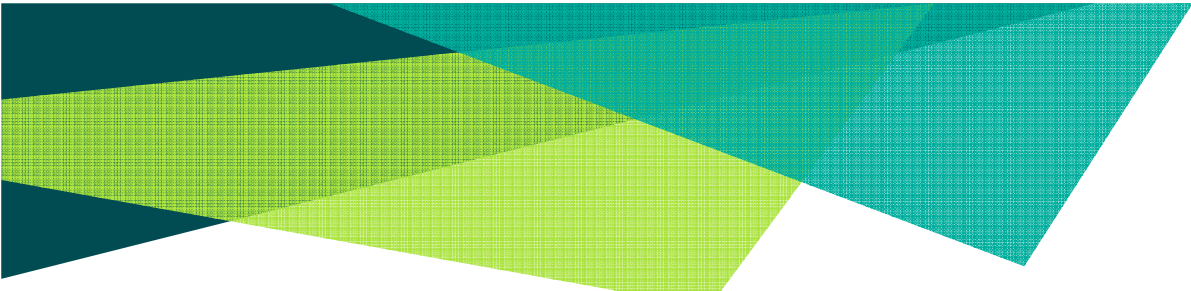
cone of doubly nonnegative matrices





Computational Experience

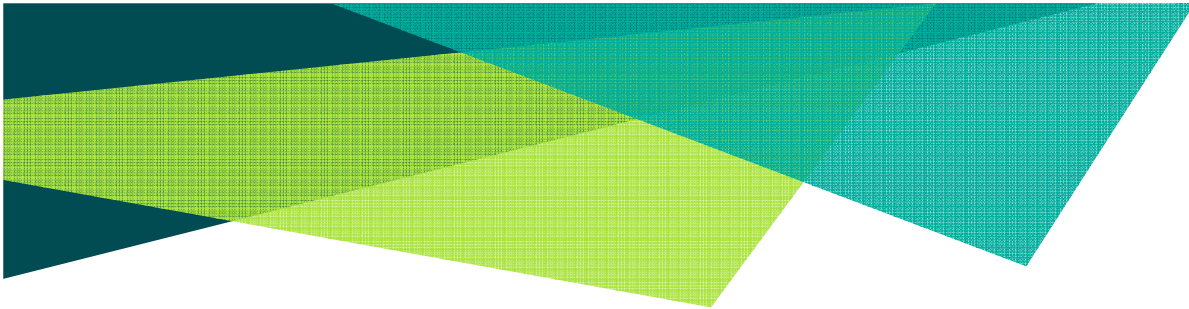




$$\begin{aligned}\psi &= \min \left\{ f(\mathbf{x}) = \frac{\mathbf{x}^\top C \mathbf{x} + 2c^\top \mathbf{x} + \gamma}{\mathbf{x}^\top B \mathbf{x} + 2\mathbf{b}^\top \mathbf{x} + \beta} : A\mathbf{x} = \mathbf{a}, \mathbf{x} \in \mathbb{R}_+^n \right\} \\ &= \min \{ \overline{C} \cdot X : \overline{B} \cdot X = 1, \overline{A} \cdot X = 0, X \in \mathcal{C}_{n+1}^* \}.\end{aligned}$$

Lower bound

$$\psi_{\text{cop}} = \min \{ \overline{C} \cdot X : \overline{B} \cdot X = 1, \overline{A} \cdot X = 0, X \in \mathcal{D}_{n+1} \},$$



Instances Generation

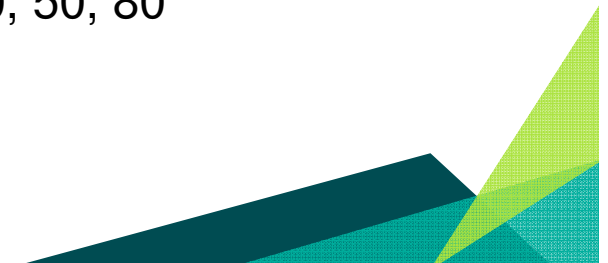
Size $n \longrightarrow n = 4, 9, 49, 79$

$$\begin{aligned} \psi &= \min \left\{ f(\mathbf{x}) = \frac{\mathbf{x}^\top C \mathbf{x} + 2c^\top \mathbf{x} + \gamma}{\mathbf{x}^\top B \mathbf{x} + 2b^\top \mathbf{x} + \beta} : A\mathbf{x} = \mathbf{a}, \mathbf{x} \in \mathbb{R}_+^n \right\} \\ &= \min \{ \overline{C} \cdot X : \overline{B} \cdot X = 1, \overline{A} \cdot X = 0, X \in \mathcal{C}_{n+1}^* \}. \end{aligned}$$

Size $(n+1, n+1)$

$$\psi_{\text{cop}} = \min \{ \overline{C} \cdot X : \overline{B} \cdot X = 1, \overline{A} \cdot X = 0, X \in \mathcal{D}_{n+1} \},$$

SDP size $\longrightarrow 5, 10, 50, 80$





Compare de LB obtained by the SDP relaxation with:

Gloptipoly 3 –

Generalized Problem of Moments - (rational polynomial optimization problem over a semialgebraic set formulated as linear moment problem)

Baron -

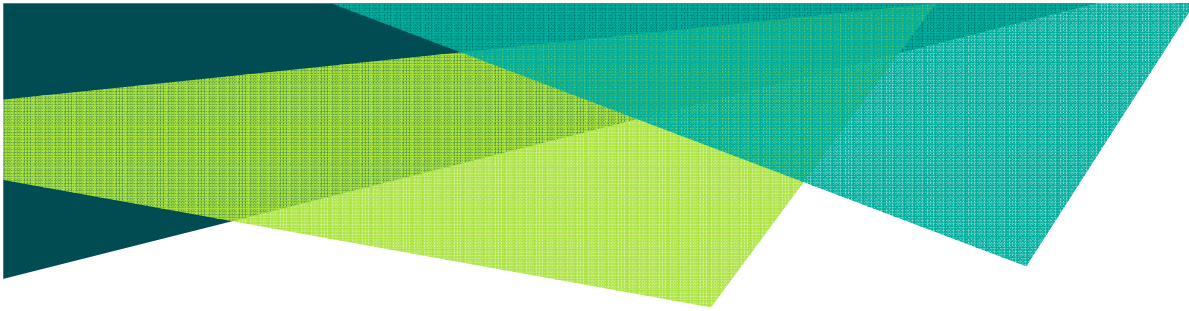
Global Optimization code - Branch and Reduce Optimization Navigator – LOWER BOUND AT ROOT, Optimal value for GAPS

Computational experience

	GPM (Gloptipoly3)	Copositive Relaxation	Copositive Relaxation with Reduction
ABJ5_0	eqs $m = 210$, order $n = 98$, dim = 2380, blocks = 7 nnz(A) = 2385 + 0, nnz(ADA) = 44100, nnz(L) = 22155 Detailed timing (sec) Pre IPM Post 7.001E-03 3.920E-01 2.002E-03	eqs $m = 15$, order $n = 33$, dim = 53, blocks = 3 nnz(A) = 55 + 0, nnz(ADA) = 225, nnz(L) = 120 Detailed timing (sec) Pre IPM Post 5.200E-02 7.001E-02 9.958E-04	eqs $m = 6$, order $n = 27$, dim = 33, blocks = 3 nnz(A) = 121 + 0, nnz(ADA) = 36, nnz(L) = 21 Detailed timing (sec) Pre IPM Post 4.003E-03 3.800E-02 9.958E-04
ABJ10_0	eqs $m = 5005$, order $n = 718$, dim = 85638, blocks = 12 nnz(A) = 138325 + 0, nnz(ADA) = 25050025, nnz(L) = 12527515 Detailed timing (sec) Pre IPM Post 8.460E-01 4.794E+02 2.800E-02	eqs $m = 55$, order $n = 113$, dim = 203, blocks = 3 nnz(A) = 210 + 0, nnz(ADA) = 3025, nnz(L) = 1540 Detailed timing (sec) Pre IPM Post 6.100E-02 6.500E-02 1.006E-03	eqs $m = 15$, order $n = 99$, dim = 119, blocks = 3 nnz(A) = 1291 + 0, nnz(ADA) = 225, nnz(L) = 120 Detailed timing (sec) Pre IPM Post 2.900E-02 5.301E-02 1.992E-03

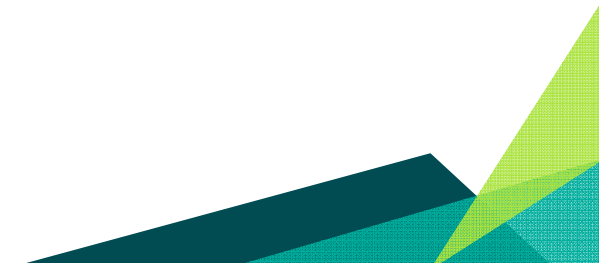
Table 1: Copositive Relaxation versus Gloptipoly 3 and BARON

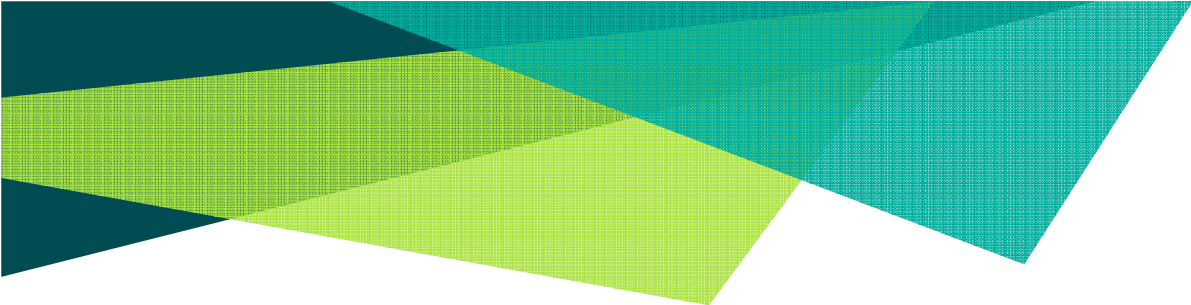
Instance	Cop R	Time1(s)	Gap	GPM R	Time2(s)	St.	root B.
ABJ5_0	-0.7865	2.700e-02	0.4837	-0.5275	1.045e+00	1	-26.1028
ABJ5_1	-0.4923	3.400e-02	1.8293	-0.5414	1.014e+00	1	-11.8308
ABJ5_2	-0.7693	2.700e-02	0.6771	-0.5089	9.672e-01	1	-11.9631
ABJ5_3	-0.3603	2.900e-02	0.9907	-0.2207	1.310e+00	1	-3.9613
ABJ5_4	-1.2562	2.700e-02	0.5467	-0.9428	9.984e-01	1	-0.8123
ABJ5_5	+0.4643	3.000e-02	0.1552	+0.2225	1.108e+00	1	-2.2940
ABJ5_6	-0.5768	3.100e-02	0.5831	-0.3671	9.828e-01	1	-8.6291
ABJ5_7	-0.0815	3.300e-02	15.2108	-0.0657	8.892e-01	1	-5.1034
ABJ5_8	-0.5946	2.600e-02	0.4752	-0.3708	9.516e-01	1	-0.4031
ABJ5_9	-0.8705	3.100e-02	0.9123	-0.5753	6.708e-01	1	-0.4553
ABJ10_0	-0.3095	3.500e-02	0.5090	-0.1962	7.010e+02	1	-23.9325
ABJ10_1	-0.6779	3.100e-02	0.4781	-0.4882	5.737e+02	1	-0.4587
ABJ10_2	+0.4144	3.400e-02	0.0533	+0.4288	6.395e+02	1	-3.4076
ABJ10_3	-0.3105	3.500e-02	1.2843	-0.1840	6.298e+02	1	-12.3357
ABJ10_4	-0.3885	3.900e-02	0.4746	-0.2689	5.122e+02	1	-0.2635
ABJ10_5	-0.7710	4.300e-02	0.2028	-0.6198	6.619e+02	1	-55.5414
ABJ10_6	-1.2861	3.100e-02	0.5562	-0.8749	7.123e+02	1	-0.8265
ABJ10_7	-0.1154	3.900e-02	1.1720	-0.0760	6.219e+02	1	-25.4559
ABJ10_8	-0.6486	3.100e-02	0.2828	-0.4558	6.239e+02	1	-0.5056
ABJ10_9	-0.3070	4.800e-02	0.5997	-0.1794	6.183e+02	1	-0.1919
ABJ50_0	-0.7435	3.238e+00	0.3552	O of M	-		-502.4740
ABJ50_1	-0.9606	2.731e+00	0.2229	O of M	-		-0.7856
ABJ50_2	-0.7844	3.192e+00	0.2786	O of M	-		-0.6135
ABJ50_3	-0.4022	2.983e+00	0.3630	O of M	-		-1463.1800
ABJ50_4	-0.2677	3.001e+00	0.8199	O of M	-		-451.7790
ABJ50_5	-0.6484	2.981e+00	0.6369	O of M	-		-0.3962
ABJ50_6	-0.5760	3.498e+00	0.3702	O of M	-		-989.5200
ABJ50_7	-0.6486	2.993e+00	0.3201	O of M	-		-0.4914
ABJ50_8	-0.5985	3.221e+00	0.3456	O of M	-		-490.0360
ABJ50_9	-0.3730	3.244e+00	0.3215	O of M	-		-626.8870
ABJ80_0	-0.4427	5.049e+01	0.5019	O of M	-		-1394.8500
ABJ80_1	-0.5806	5.532e+01	0.2984	O of M	-		-0.4472
ABJ80_2	-0.8597	5.532e+01	0.2869	O of M	-		-0.6681
ABJ80_3	-0.4345	5.519e+01	0.3302	O of M	-		-1849.5000
ABJ80_4	-0.8625	5.101e+01	0.3214	O of M	-		-0.6528
ABJ80_5	-0.4670	5.117e+01	0.3301	O of M	-		-0.3511
ABJ80_6	-0.3473	5.539e+01	0.6090	O of M	-		-2488.4700
ABJ80_7	-0.5883	5.105e+01	0.3607	O of M	-		-1487.1000
ABJ80_8	-0.4181	5.532e+01	0.5004	O of M	-		-736.0130
ABJ80_9	-0.7023	5.099e+01	0.3568	O of M	-		-0.5177



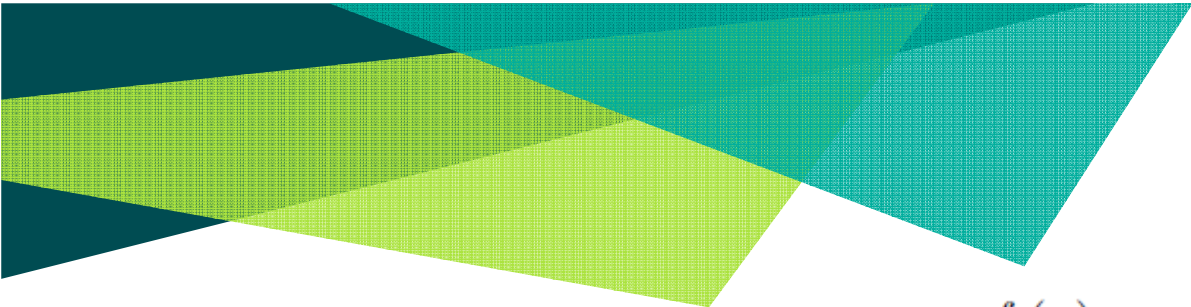
Linear discriminant problems 8x8

UB	Sol	UB
1,00E+09	6,17E-02	6,17E-02
1,00E+09	1,47E-01	1,52E-01
1,00E+09	2,56E-01	2,60E-01
1,00E+09	1,53E-01	1,56E-01
1,00E+09	1,19E-01	1,20E-01
1,00E+09	1,91E-01	1,91E-01
1,00E+09	2,24E-01	2,35E-01
1,00E+09	2,42E-01	2,42E-01
1,00E+09	1,32E-01	1,32E-01
1,00E+09	3,46E-01	3,47E-01

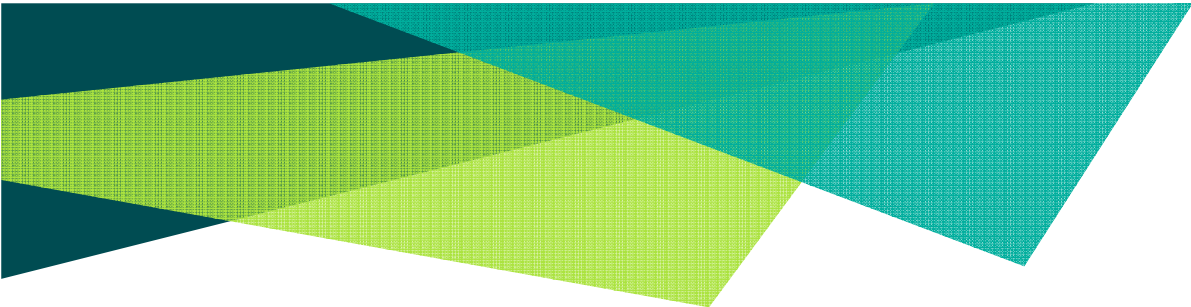




And minimax fractional problems


$$\min_{x \in \Omega} \max_{i \in I} \frac{f_i(x)}{g_i(x)}.$$

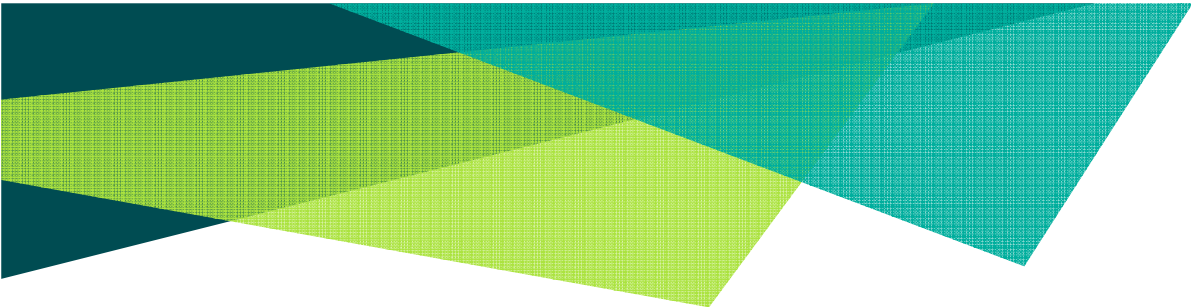
- Allows the decision maker to compute the best strategy under the worst-case scenario.
- The solution value will not deteriorate whichever scenario turns out to be the true one.
- The real solution evaluation will be at least as good as the min-max value.
- Applications of single ratio can be directly extended cases where there is some uncertainty related to outside factors.



Copositive reformulation

$$(\text{MMDFP}) \quad \min_{x \in \Omega} \max_{i \in I} \frac{x^\top Q_i x + 2b_i^\top x + c_i}{r_i^\top x + d_i}.$$

$$\Omega = \{x \in \mathbb{R}_+^n : Ax = a, x^\top A_q x + a_q x + \alpha_q \leq 0 \text{ for all } q \in [1:p]\}$$

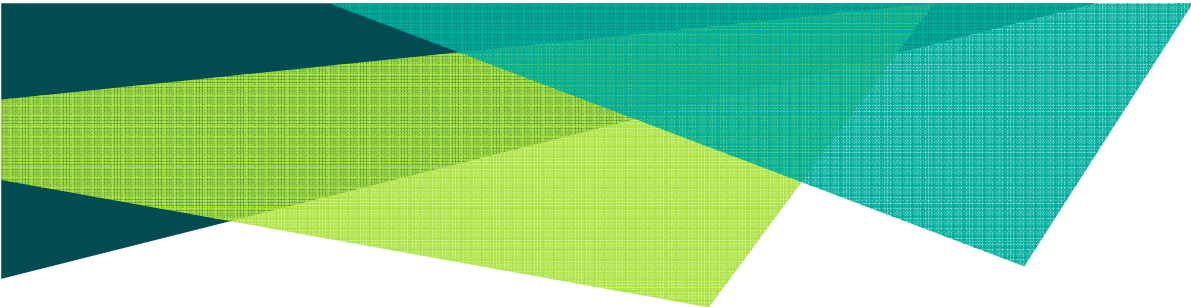


We use a Shor lifting: $y^\top = [1 \ x^\top]$ and for $i \in I$ abbreviate by

$$\hat{h}(y) = \max_{i \in I} \frac{y^\top \hat{Q}_i y}{\hat{r}_i^\top y}$$

with

$$\hat{Q}_i = \begin{bmatrix} c_i & b_i^\top \\ b_i & Q_i \end{bmatrix} \quad \text{and} \quad \hat{r}_i = \begin{bmatrix} d_i \\ 2r_i \end{bmatrix}.$$

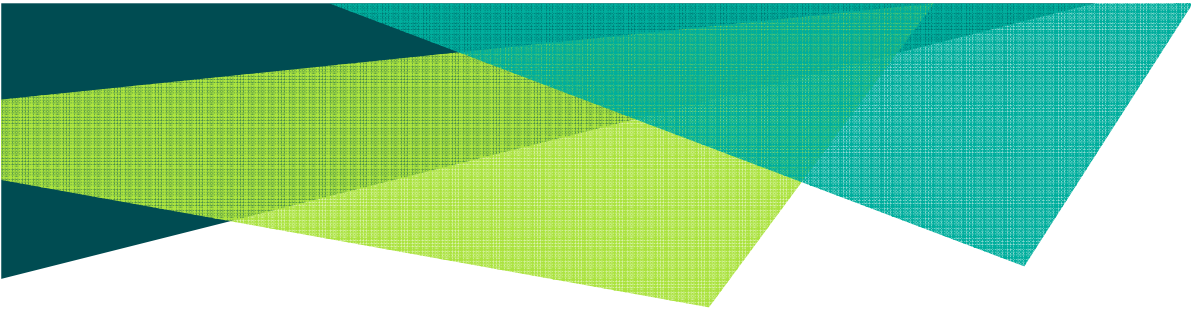


Next we :

$$Ax = a \iff \|Ax - a\|^2 \leq 0 \iff y^\top \widehat{A}_0 y \leq 0,$$

where

$$\widehat{A}_0 = \begin{bmatrix} a^\top a & -a^\top A \\ -A^\top a & A^\top A \end{bmatrix}.$$



Likewise, homogenize the quadratic constraints by introducing, for all $q \in [1:p]$,

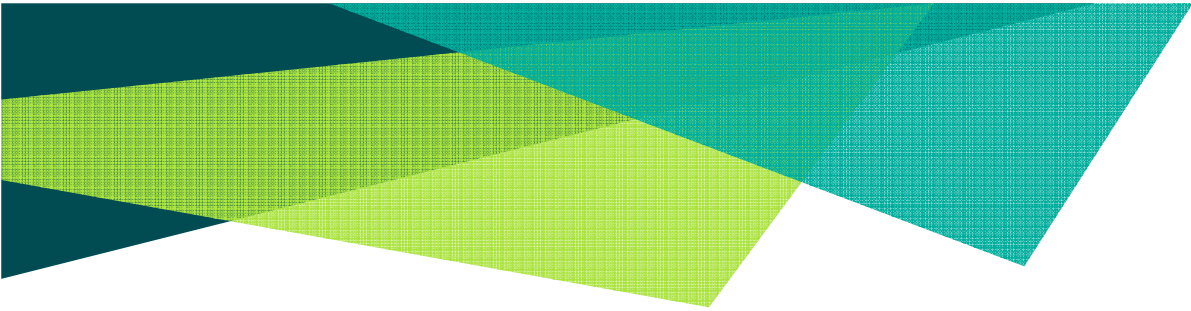
$$\widehat{A}_q = \begin{bmatrix} \alpha_q & \mathbf{a}_q^\top \\ \mathbf{a}_q & A_q \end{bmatrix}.$$

So, denoting

$$\widehat{\Omega} = \left\{ y \in \mathbb{R}_+^{n+1} : y_0 = 1, y^\top \widehat{A}_q y \leq 0 \text{ for all } q \in [0:p] \right\},$$

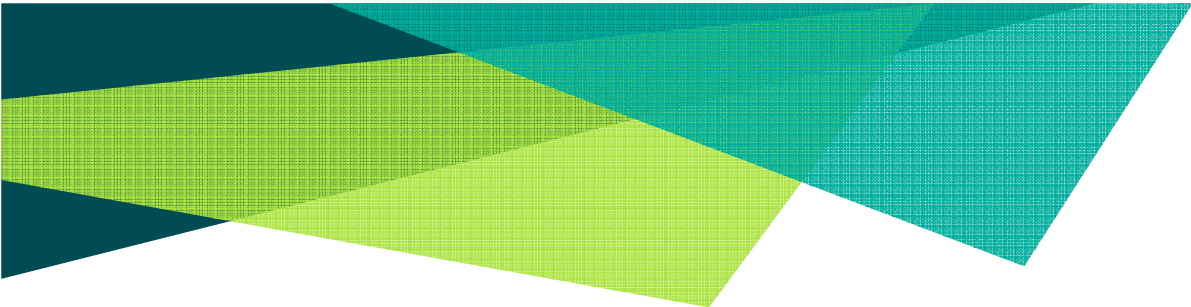
we arrive at

$$\lambda^* = \min_{y \in \widehat{\Omega}} \widehat{h}(y) = \min_{y \in \widehat{\Omega}} \max_{i \in I} \frac{y^\top \widehat{Q}_i y}{\widehat{r}_i^\top y}. \quad (12)$$



we introduce another variable $v \in \mathbb{R}$ and obtain

$$\begin{aligned}\lambda^* &= \min_{y \in \widehat{\Omega}} \left\{ \max_{i \in I} \frac{y^\top \widehat{Q}_i y}{\widehat{r}_i^\top y} \right\} \\ &= \min_{(y,v) \in \widehat{\Omega} \times \mathbb{R}} \left\{ v : \frac{y^\top \widehat{Q}_i y}{\widehat{r}_i^\top y} \leq v \text{ for all } i \in I \right\} \\ &= \min_{(y,v) \in \widehat{\Omega} \times \mathbb{R}} \left\{ v : y^\top \widehat{Q}_i y \leq v \widehat{r}_i^\top y \text{ for all } i \in I \right\} .\end{aligned}$$



Now considering $z = [y^\top \ v]^\top$ and

$$\begin{aligned}\check{Q}_i &= \begin{bmatrix} \widehat{Q}_i & \mathbf{o} \\ \mathbf{o}^\top & 0 \end{bmatrix} \quad \text{for } i \in I, \\ \check{R}_i &= \begin{bmatrix} 0 & \frac{1}{2}\widehat{r}_i \\ \frac{1}{2}\widehat{r}_i^\top & 0 \end{bmatrix} \quad \text{for } i \in I, \\ \check{A}_q &= \begin{bmatrix} \widehat{A}_q & \mathbf{o} \\ \mathbf{o}^\top & 0 \end{bmatrix} \quad \text{for } q \in [0:m],\end{aligned}$$

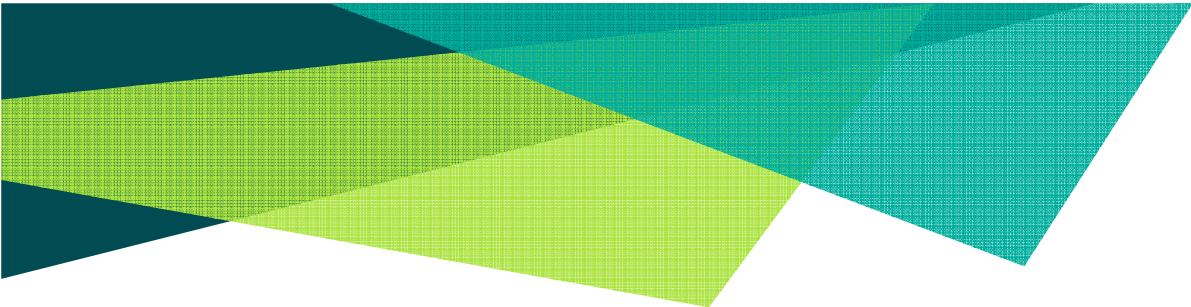
we obtain

$$\begin{aligned}
\lambda^* &= \\
&= \min_{z \in \mathbb{R}_+^{n+1}} \left\{ z_{n+1} : z_0 = 1, z^\top \check{Q}_i z \leq z^\top \check{R}_i z, i \in I, z^\top \check{A}_q z \leq 0, q \in [0:p] \right\}. \\
&= \min_{z \in \mathbb{R}_+^{n+1}} \left\{ z_{n+1} : z_0 = 1, z^\top (\check{Q}_i - \check{R}_i) z \leq 0, i \in I, z^\top \check{A}_q z \leq 0, q \in [0:p] \right\}.
\end{aligned}$$

$$X = zz^\top, (z_{n+1}^* \geq 0) \text{ and with } z^\top W z = W \bullet X$$

$$\begin{aligned}
\gamma^* &= \\
&\min_{X \in \mathcal{C}_{n+2}^{rk1}} \left\{ X_{n+1,n+1} : X_{00} = 1, (\check{Q}_i - \check{R}_i) \bullet X \leq 0, i \in I, \check{A}_q \bullet X \leq 0, q \in [0:p] \right\},
\end{aligned}$$

where $\mathcal{C}_{n+2}^{rk1} = \{X \in \mathcal{C}_{n+2} : \text{rank } X = 1\}$.



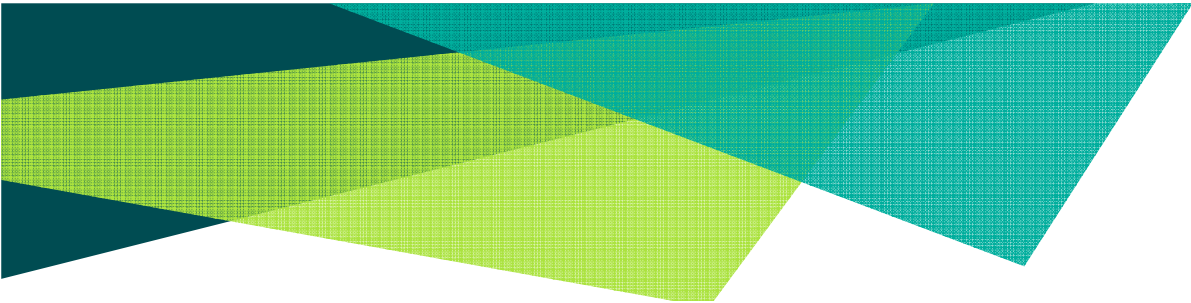
Dropping the rank constraint leads to the copositive relaxation

$$\gamma_{CP}^* = \min_{X \in \mathcal{C}_{n+2}} \left\{ X_{n+1,n+1} : X_{00} = 1, (\check{Q}_i - \check{R}_i) \bullet X \leq 0, i \in I, \check{A}_q \bullet X \leq 0, \right. \\ \left. q \in [0:p] \right\}$$

with its dual

$$\gamma_{COP}^* = \sup_{u \in \mathbb{R}_+^{m+q+2}} \left\{ u_0 : E_{n+1} - u_0 E_0 - \sum_{i=1}^m u_i (\check{Q}_i - \check{R}_i) - \sum_{q=0}^p \mu_q \check{A}_q \in \mathcal{C}_{n+2}^* \right\},$$

where $E_k \bullet X_k = X_{kk}$.



Numerical experiments

- PC, Intel(R) Core(TM) i7-2640M, 2.80 Ghz, 400 GB RAM.
- Matlab 2013Ra was used to run the global optimization solver BARON
- $\lambda^* = \min \left\{ v : \frac{f_i(x)}{g_i(x)} \leq v, i \in I, Ax = a, A_q x \leq a_q, x \geq 0, v_l \leq v \leq v_u \right\}$
- SDPT3(4.0)/Octave,
- interface YALMIP was used to call SDPT3.
- Test instances were randomly generated. $m = 3, 5, 10$ ratios and $n \in \{5, 25, 50, 75\}$.

$$\text{Gap1} = 100 \frac{\text{BARON UB} - \text{BARON LB}}{\text{BARON UB}}$$

$$\text{Gap0} = 100 \frac{\text{BARON UB} - \text{YLB}}{\text{BARON UB}}$$

$$\text{Gap2} = 100 \frac{\text{BARON UB} - \text{BARON LB}}{\text{BARON UB}}$$

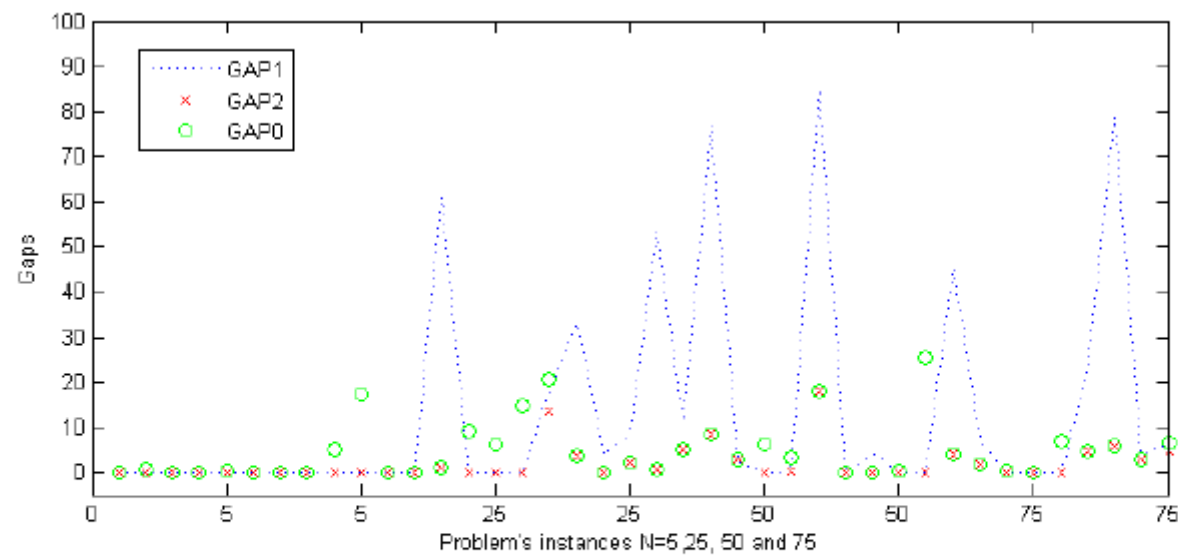


Figure 3: Relative gaps for the $m = 5$ instances



Conclusions



**Better than a positive
friendship just a copositive
one!**



Future work?



THANK YOU MANUEL!

